Digital temperature controller

# **AX** series

# INSTRUCTION MANUAL

Thank you for purchasing HANYOUNG product. Please check whether the product is the exactly same as you ordered. Before using the product, please read this instruction manual carefully.



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# Safety information –

Before operating, please read through the safety information carefully for proper usage This safety information contains very important information regarding the safety issues so please follow these instructions at all times. This safety information is composed of Danger, Warning and Caution,



The electric shock may occur in the input/output terminal so please never let your body and/or conductive substance to be contacted by the input/output terminal.



- · If you are concerned about the serious troubles such as break down of the product and etc, please in stall proper protective circuit on the outside in order to prevent such incident from occurrina.
- · The power switch and fuse are not installed on this product so users need to install them separately on the outside. (Fuse rating: 250 V 0,5A)
- Please supply in the rated power supply votage in order to prevent this product from breaking
- · This is not designed as explosion-protective structure so avoid using this product at places where gas inflammability and explosive gases exist.
- . Do not supply in the power until all wiring is fully completed in order to prevent the product from breaking down and prevent users from getting electric shock
- · Do not disassemble, manufacture, upgrade and repair the product by yourself. Doing so will break down the product, generate the electric shock and cause malfunction to occur.
- · Please turn OFF the product and disassemble the product. Not doing so will break down the product, generate the electric shock and cause malfunction to occur. Bectric shock may occur when operating this product so please install this product to the panel and use it



- The contents of this manual may be changed without prior notification
- · Please check for correct model type and specification
- Please check for any damage or abnormality may caused during ship ment.
- Please use this product at following range.

Ambient temperature  $-5 \sim 50$  °C (when installing them close to each other, max 40 °C) / humidity:  $35 \sim 85\%$  RH (but without diew condensation)

- · Please avoid the places where corrosive gas(especially noxious gas, ammonia and etc) and inflammable gas exist
- · Please do not use this product at places where the vibration or impact is applied directly.
- · Please avoid the places where liquid, oil, medical substances, dust, salt or iron contents exist(avoid place of pollution level 1 or 2)
- . Do not clean the product with the organic solvent such as alcohols, benzene and etc. (Use neutral detergents)
- · Please avoid the places where huge inductive interference exists and places where static electricity/self noise are generated.
- · Please avoid the places where heat accumulates due to the direct sunlight, radiation and etc
- Please use it at altitude below the 2000 m.
- · If the device is touched or contacted by water then short-circuit and fire may occur so please inspect the device carefully
- · With the thermocouple input, please use the stated compensation cable. (Using regular compensation cable will generate the temperature error)
- With the RTD input, please use the cable with less lead-wire resistance and no difference in the resistance among 3-wires, (Using regular cable will generate the temperature error) · For the input signal wire, please avoid from the power line and load line in order to avoid from
- the induction noise • Se parate the input signal wire and output signal wire and if separating them from each other is
- impossible, then please use the shield wire for the input signal wire For the thermocouple, please use It as the un-grounding type. (When using the grounding type.)
- malfunction may occur due to the electric leak age) • When there are too much noises generating from the power, we recommend using the insulation Trans and noise filter. Noise filter must be mounted to the panel or etc that is grounded and
- Tight ly twisting the power line meter will reduce the noise generation
- If alarm function is not set properly, alarm will not be generated when it should so please check for the operation before running the product.

please try to make the wiring of output and power terminal meter as short as possible.

· When replacing the sensor, please turn OFF the power

### • If operation frequency is too high (such as proportional operation and etc) and connecting the maximum rated load to output relay will shorten the life expectancy therefore, please use the auxiliary relay. We recommend using the SSR output type in such cases.

- When using the electrical switch: Set proportional cycle min 20 sec
- When using the SSR: Set proportional cycle min 1 sec
- · Do not wire anything to the un-using terminal
- Please check the polarity of terminal before wiring.
- When installing this product to the panel please use the authorized switch or circuit breaker (authorized by IEC 60947-1, or IEC 60947-3)
- · Please install the switch or circuit breaker close to the operator for users' convenience
- Because switch or circuit breaker is being installed, please make a note on the panel that operating the switch or circuit breaker will block the power.
- · We recommend the continuous inspection and repair in order to use it safely for a long period of time,
- Some parts in this product have life expectancy and glets old as time elapses.
- The warranty period is one year including the parts only under the condition where the product is used properly
- It needs the preparation time for contact output when supplying in the power. When applied as signal to the external interlock circuit and etc. please jointly use the delay lelay.
- . When changing the instrument or if the product broke down, users can replace with the prepared product but even suffix code stays same, operation may differ due to the parameter difference so please check for the compatibility and perform such action.

# Suffix code

Model Co		de	Information		
AX	□ -			Digital temperature controller (multi input: K, J, Pt100 Ω)	
	2			AX2:48 X96 mm	
	3			AX3:96 X 48 mm	
Dimension	4			AX4:48 X 48 mm	
	7	-		AX7:72 X72 mm	
	9			AX9: 96 X 96 mm	
				SSR + Relay1 + Relay2	
		2		SSR + Relay1 + Relay2 + Relay3	
Output se	Output selection			4 - 20 mA + Relay2	
		4		4 - 20 mA + Relay2 + Relay3	
Power supply voltage A			Α	100 - 240 V a.c 50/60 Hz	

\* Relay output operates as control output, alarm output and LBA output depending on the internal parameter setting.

# Input:

- Input selection : Multi input(Thermocouple : K, J, IEC584-1), (RTD : Pt 100  $\Omega$ , IEC751).
- Input sampling time: 0.1 s
- In put impedance: 1 Mo max
- Allowable wiring resistance: 10 Ω/ 1wi re max(RTD), but resistances among 3 wi res should be same
- Allowable input voltage: 10 V d.c

### Performance

Display accuracy ±0,3 % of F,S	
Input resolution	Thermocouple: 0.1 °C (K2, J), 0.5 °C (K1)
inpat resolution	RTD: 0.03 °C, (0.1 °F)
In su lati on re sista noe	More than 20 Mg 500V d.c for 1min (Primary terminal-Secondary terminal)
Dielectric strength	2300V a.c 50/60Hz, for 1 min (Primary terminal-Secondary terminal)

# Range and input code

Classifi	Codo	lanut tuna	Range			
cation	Code	Input type	Celsius(°C)	Fahrenheit(°F)		
F.1		К	-100 ∼ 1200 °C	-148 ~ 2192 °F		
Thermocouple	55	K	-100,0 ~ 500,0 ℃	−148 ~ 932 °F		
	ŗ	J	-100.0 ~ 500.0 ℃	-148 ~ 932 °F		
R⊺D	PŁ	Pt100 Ω	-100.0 ~ 400.0 ℃	-148.0 ~ 752.0 °F		

# Control function and output —

- Control type: PID control, P control, ON/OFF control
- · Auto-tuning: PID operation by the auto-tuning
- ON/OFF control: When PV > SV, it generates 0 % output. When PV < SV, it generates
- 100 % output. (Only when control hysteresis is 0)
- · Manual reset: Users set within the range from 0 % to 100 %.
- · Control output operation: Direct action/Reverse action (selected by the parameter setting)
- · Control output: Relay output/voltage pulse output (SSR output)
- \* Selected by the parameter setting

	1a contact (Resistive load)				
Relay	Relay output can be selected maximum 3 and relay control output is displayed as RLY1.  Alarm output 2 contacts (AL1, AL2) and LBA output are assigned by the users among RLY1, RLY2 and RLY3.				
SSR	CYC	12 - 15 V dc pulse voltage (resistive load min 600 Ω			
0.0.10	PHA	12 13 v qc pase voltage (resistive road mirri 000 g)			
4 – 20 mA	Accuracy: 0.5 % of F.S, Ripple Vp-p : 0.3 % of F.S, Resistive load: Max 600 $\Omega$				

### Specification

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Model	AX2	AX3	AX4	AX7	AX9
Power supply voltage	100 - 240 V ac 50/60 Hz				
Voltage fluctuation	±10 % of power supply voltage				
Power consumption	5,5 VA max				
Ambient temperature	emperature −5 ~ 50 °C				
Ambient humidity 35 ~ 85 % R H (But without dew				dew ∞nder	rsation)
Vibration (resistance)	10 - 55 Hz, 0,75 mm, X Y Z each in X, Y and Z directions for 2 hour				
Shock (resistance)	300 m/s² to 6 directions each 3 times				
Weight	320 g	320 g	180 g	300 g	400 g

<sup>\*</sup> Weight included the weight of box

# Function and name of each part



No	Model		Information
1	Process value (PV)		Display the current temperature in the operation screen
2	Se	t value (SV)	Display the set temperature in the operation screen
3		Up Key	Ohange the operation screen, increase the set value, move to the parameter setting mode
4		Down Key	•Decrease the set value, move to the parameter setting mode
\$		Shift Key	Shift to the set value digits  Move from operation screen – users  Move from operator – setting mode
6	MODE	Mode Key	Move from operation screen - users  Move from operator - setting mode
	AT		Light ON with the PID auto tuning
	OUT	0	Light ON with the control output operation
7	AL1	Operation indicators	Light ON with the Alarm1 operation
	AL2		Light ON with the Alarm2 operation
	LBA		Light ON with the Loop break alarm operation

# Important function explanation

■ Heating/Cooling output action selection

Able to select the reverse action (heating control) or direct action (cooling control) output by the [Er.d parameter

### ■ PID auto tuning (A.T) function

Auto tuning function measures, computes and sets the optimum PID or ARW constant automatically. After supplying power in and while temperature is increasing, press the set key set key and key synchronously for 2 sec, to begin the auto tuning. When auto tuning is finished, tuning operation will be ended automatically.

#### ■ ON/OFF control setting method

Usually temperature controller performs the temperature control by "PID control method" which is done by the PI auto tuning. However, ON/OFF control method is used when controlling the refrigerator, fan, solenoid valve and etc. When users want to set the temperature controller as ON/OFF control mode, set the setting value of proportional band as ££rā within the "general setting parameter." Here, #35 (hysteresis) parameter will be displayed. Prevent such action to occur by setting the desired ON/OFF action range.

## ■ ២០៩೬ display

When input break (sensor break) occurs or exceeds the maximum temperature range, bollwill be displayed in the measured value displaying unit.

#### ■ Output terminal and output signal

#### RLY signal allocation

AX Series has maximum 3 relay contact output. These 3 relay contact outputs are called as RLY1 to RLY3. Please refer to the connection diagram for the terminal position. The control signal and alarm signal are generated from the RLY1, Selecting the rLY in the aLkr parameter will yield the control signal in the RLY1. Selecting the 55r in the often parameter will able users to select the alarm signal and make the output, Users can select the alarm signal and make the output in the RLY2 and RLY3,

#### ■ Alarm

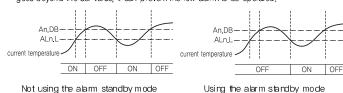
### · Using the alarm

AX series supports 2 independent alarms (AL1 and AL2). These alarms can allocate AL1 or Al 2 signal in the R Y1 RIY2 and RIY3 and be used. If alarm signal is not allocated in the RLY1 to RLY3 then the menu related to the alarm will not be displayed.

#### · Alarm hold action

If there is no standby action function, supply the power in then the LOW alarm will become ON while temperature is increasing

In order to prevent the low alarm to become ON during temperature is increasing, add the stand by action function so from the point when supplying in the power to until the value goes beyond the set value, it can prevent the low alarm to be operated.



## · Alarm output LOCK

It the Roah value is ON, Alarm is not cancelled evenif it becomes the alarm cancel condition. If users want to stop the alarm forcedly, please press the \textbf{\textit{L}} key for approx 2 sec.

(An HD=ON)

#### ■ LBA (L.B.A: Loop Break Alarm)

(An,HD=OFF)

LBA function starts to measure time from the moment when the PID computed value becomes 0 % or 100 %. Also, from this point, this function detects heater break sensor break manipulator malfunction and etc by comparing the changed amount of measured value in each set time. Also, it can set the LBA dead band in order to prevent any malfunction to happen in the normal control loop

#### ① When control output value which obtained by PID operation is 100 %.

If the temperature does increase more than  $LbR_{\mu}$  value within the LBA set time, LBA output will become ON

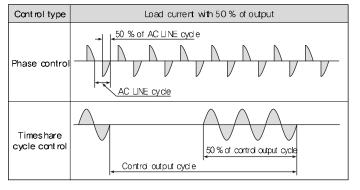
# 2 When control output value which obtained by PID operation is 0 %,

If the temperature does decrease more than  $L\,bR_{LL}$  value within the LBA set time, LBA output will become ON

# ■ Timeshare cycle control and phase control of Voltage pulse output

When selecting the control output type as SSR users will be able to select the types for voltage pulse output. The timeshare cycle control turns ON/OFF the output by proportioning the certain time to an output amount in cycle. Set the cycle of control output in the [] parameter.

Within the half cycle of power wave shape, the phase control (depending on an output amount controls an output amount by computing the output ON phase. However, when using the phase control users must use the RANDOM ON/OFF type SSR



# ■ Operation mode

Supplying in the power after finish wiring will display the current temperature, Pressing the MoDE key will display the set temperature and output amount alternatively on the set value (SV) displaying unit,

# ■ User setup mode

User setup mode is the setting mode that sets the set value that is changed by users frequently such as alarm set value and loop break alarm (LBA), it made the parameter of user setup mode to be displayed on the operator setup mode that allows users to set easily (divided the setting level).

Set Value(SV) can be set up in the User setup mode (When 5u is displayed, push shift key( ) to change set value) Change set value by . . key and push MODE key.

Symb ol (PV)	Lists	Information	Display condition	Default value (SV)
50	set temperature	EU 0 ~ 100 %	at all times	EU 0 %
RL IL	Alam 1 low value			EU 0 %
AL IH	Alarm 1 high value	EU 0 ~ 100 % or		EU 100 %
R Idb	Alam 1 dead zone	EUS 0 ~ 100 %	When RLYn	EUS 0 %
RL Z.L	Alarm 2 low value	(temperature unit)	ALn is set	EU 0 %
RL 2H	Alarm 2 high value	(temperature unit)		EU 100 %
82.db	Alam 2 dead zone			EUS 0 %
LbRE	Loop break alarm time	0 ~ 7200초	When LBA is set	480
LbRu	Loop break alam temperature	0 ~ 100 ℃ (°F)	in the RLYn	2
LbRd	Loop break alarm dead zone	0 ~ 100 ℃ (°F)		2
		[]: NO LOCK function		
LoE	KEY lock	1 : Operator setup mode LCCK, Auto-tuning prohibited	at all times	0
		2: Operator and user set up mode LOOK		

#### ■ Operator setup mode

Symbol

Operator setup mode is the setting mode that sets the specification of temperature controller when engineer installs it for the first time. Pressing the MODE key and < key synchronously in the operation screen or user setup mode will enter into the operator setup MODE and keys one more time for 2 sec will return to the operation screen.

display

Default

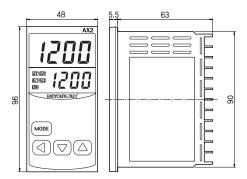
(PV)	lists	info mation	display condition	Detault value
I nP	Input condition	L I : K thermcouple (Not display the decimal points) L Z : (Sisplays the decimal points) L : (Sisplays the decimal points)	At all times	Εl
Unl E	Temperature unit		At all times	<u> </u>
dР	Decimal point	ON(YES)	Select decimal point	n a
ы яѕ	Input compensation	OFF(NO)  -100 ~ 100(sensor input value + BIAS)	At all times	П
FILE	Input filter time	0 ~ 120 sec	At all times	
SLH	High setting limitation	EU 0 ~ 100 %	At all times	1200
SLL	Low setting limitation	EJ 0 ~ 100 %	At all times	- 100
ο[tr	Control output type	55r: SSR operating voltage pulse output		551
55r£	Voltage pulse output type	EYE: Timeshare proportional control PHR: SSR phase control (continuously proportioning)	When selected SSR control output	[4[
ĽŁ	Control output cycle	0 ~ 1000 sec	When 55r.Ł is CYC or a.E.Łr. is RLY	2
[Er.d	Control output action	rEu: Reverse action (heating control)  d1 r: Direct action (cooling control)	At all times	rEu
[Łrň	Control type	Pt d: PID control P: P control (proportional control) anaF: ON/OFF control	At all times	PI d
РЬ	Proportional band	1 (0,1) ~ EUS 100 %	When it is not ON/OFF control	30
1	Integral time	0 ~ 3600 sec	With PID control	240
Ь	Derivative time	0 ~ 3600 sec	With PID control	60
ñr	Manual reset	0.0 ~ 100.0 %	With Picontrol	50.0
XY5	Control hysteresis	EUS 0 ~ 100 %(Temperature unit)	With ON/OFF control	2
Po	Output amount with input break	0 ~ 100 %	At all times	0.0
LFAI	Relay1 property	RL1: Alarm 1 output RL2: Alarm 2 output Lb8: LBA output	When output selection is 1 or 2 and officers RLY	nan
rL45	Relay 2 property	nan: Not using RL 1: Alarm 1 output RL2: Alarm 2 output Lb8: LBA output	At all times	AL I
rLY3	Relay 3 property	non: Not using RLI: Alarm 1 output RLZ: Alarm 2 output LbR: LBA output	At all times (Option)	AL 2
R lõd	Alarm 1 mode	non: Not using		[
ח וחם	(Alarm 1 or 2)	[: High alarm		L
RZňd	Alarm 2 mode (Alarm 1 or 2)	]: Low alarm -[]-: Alarm within range ][: Alarm not within range		]
R IFA	Alarm 1 type	Rb5 : ABS(Absolute alarm)	When AL1 or AL2	R65
R2F2	Alarm 2 type	dEu: DEV(Deviation alarm)	is set in	RbS
R IHd	Alarm 1 standby mode	ωFF: O⊞ (not using the standby mode)	RLY 1, 2, 3	oFF
R2Hd	Alarm 2 standby mode	•		oFF
R 189	Alarm 1 delay time	0 ∼ 9999 sec		0
859A	Alarm 2 delay time			0
R loX	Alarm 1 output LOCK	<ul> <li>FF: Alarm output return action</li> <li>Alarm output maintain action</li> </ul>		oFF
R2 <sub>0</sub> X	Alarm 2 output LOCK	Aariii output maimain action		oFF

Dimension and panel cutout, connection diagram

[unit:mm]

AX2

Dimension

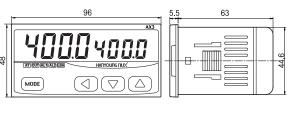


● Panel cutout

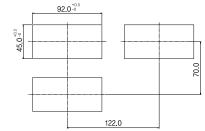
Connection diagram

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Dimension

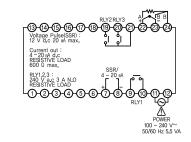


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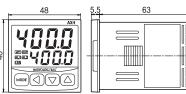


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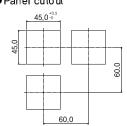
Connection diagram



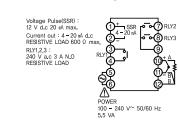
Dimension



● Panel cutout

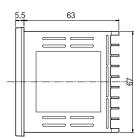


Connection diagram

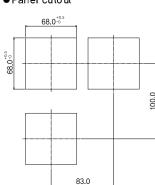


Dimension

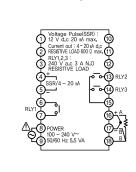




● Panel cutout



Connection diagram



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Dimension

MODE  $\triangleleft$  )( $\nabla$ )

● Panel cutout

Connection diagram

